

Unit IV Nonlinear Waves, Shocks and Turbulence - An Introduction

Previously discussed:

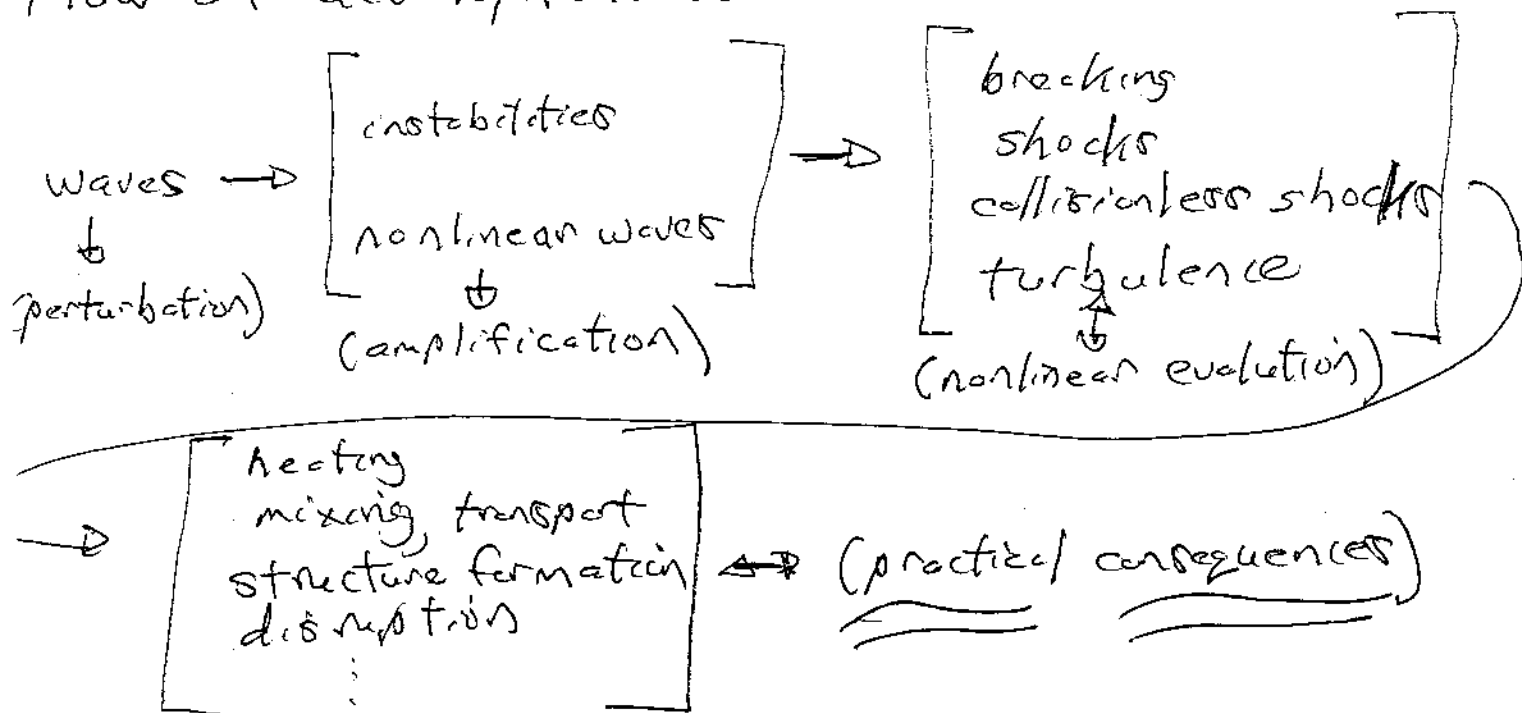
→ basic waves in MHD, i.e. structure of MHD 'stiffness matrix'

→ SW and MHD instabilities (an introduction)

Now are concerned with evolving waves and instabilities i.e. what happens? →

- nonlinear amplification of MHD waves, wavebreaking
- shocks and collisionless shocks in MHD,
- turbulence

Flow of development is:



Proceed via :

i) Nonlinear Waves

- a) Wave Action and Eikonal Theory
- b) Wave Amplification and Breacking
- c) Disparate Scale Interaction

ii) \wedge Shocks and collisionless shocks

- a) shocks in kinematic waves
- b) shocks in fluids and MHD
- c) collisionless shocks in plasmas

iii) Fluid and MHD Turbulence - An Introduction

then, ... \Rightarrow Applications to Laboratory and Solar Plasmas

① \rightarrow current and magnetic configurations (DW with J_0)

② \rightarrow ∇p stability of confinement devices

③ \rightarrow magnetic fields and buoyancy in the sun.

→ Nonlinear Waves

Read: { ① Kulsrud 5.5, 5.6
 ② Whitham, Chapt. 11
 ③ Landau, Lifshitz Fluids Chapt.

→ have considered plane waves in uniform media
 i.e. $\underline{\underline{\epsilon}} \sim \underline{\underline{\epsilon}}_0 e^{i(\underline{k} \cdot \underline{x} - \omega t)}$

→ what if media non-uniform, but slowly varying

i.e. $\frac{1}{c^2} \frac{\partial^2 \hat{\phi}}{\partial t^2} = \nabla^2 \hat{\phi}$ (caustics)

with $c^2 = c^2 / n^2(\underline{x})$

↳ index of refraction
 (can be time dependent)

then for $\left| \frac{\nabla n}{n} \right| \ll |k|$, can write

$$\hat{\phi} = \hat{\phi}_0 e^{i\phi(\underline{x}, t)}$$

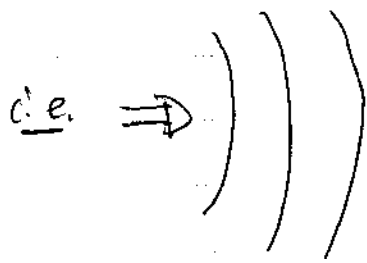
where $\phi \sim O(1/\epsilon)$

→ phase contains fastest variation

then have:

$$\boxed{\frac{n(\underline{x})^2}{c_0^2} \left(\frac{\partial \phi}{\partial t} \right)^2 = \left(\nabla \phi \right)^2}$$

→ eikonal equation
 for phase front
 function ϕ



i.e. \Rightarrow iso- ϕ surfaces $\Rightarrow \nabla \phi \Rightarrow$ direction of propagation

Clear analogy with plane waves \Rightarrow

$$\underline{\nabla} \phi \leftrightarrow \underline{k}$$

$$-\frac{\partial \phi}{\partial t} \leftrightarrow \omega$$

[if Λ time independent,
 $\omega = \text{const.}$ for linear wave]

so eikonal equation is:

$$\frac{n(x)^2 \omega^2}{c_0^2} = k^2$$

so, have for medium
with no explicit time dependence,

\hookrightarrow local dispersion
relation

$$d\phi = \frac{\partial \phi}{\partial x} \cdot dx + \frac{\partial \phi}{\partial t} dt$$

$$= \underline{k}(x) \cdot d\underline{x} - \omega(\underline{k}, x) dt$$

\hookrightarrow via Eikonal Equation

$$\therefore \frac{d\phi}{dt} = \underline{k}(x) \cdot \frac{d\underline{x}}{dt} - \omega(\underline{k}, x)$$

\Rightarrow

$$\underline{\Phi} = \int dt \left[\underline{k}(x) \cdot \underline{\dot{x}} - \omega \right]$$

but recall:

$$\underbrace{S}_{\text{action}} = \int dt \left(\underbrace{p\dot{q}}_{\text{Hamiltonian}} - H \right)$$

and $\delta S = 0 \Rightarrow$ equations of motion

can immediately note analogy:

Hamiltonian Dynamics	} Rays/Eikonal Theory
$\underline{p} \rightarrow$ momentum ($= \partial L / \partial \dot{q}$)	$\underline{k} \quad (= \nabla \phi)$
$\underline{q} \rightarrow$ gen. coord	$\underline{x} \quad$ (phase front position)
$H \rightarrow$ Hamiltonian	$\omega \quad$ (frequency)
$\phi \rightarrow$ phase function	$S \rightarrow$ action

and recall Hamilton-Jacobi Equation:

$$\frac{\partial S}{\partial t} + H\left(q, \frac{\partial S}{\partial q}\right) = 0$$

\Rightarrow phase evolution equation:

$$\frac{\partial \phi}{\partial t} + \omega(\underline{k}, \underline{x}) = 0$$

$$\underline{k} = \underline{\nabla} \phi$$

exact isomorphism

∴ just as advance Hamiltonian variables
on time via Hamilton's Eqn. of Motion,
i.e.

$$\frac{d\underline{p}}{dt} = - \frac{\partial H}{\partial \underline{q}}, \quad \frac{d\underline{q}}{dt} = \frac{\partial H}{\partial \underline{p}}$$

then, can advance \underline{k} and \underline{x} analogously
by:

Ray
Eikonal
Equations

$$\frac{d\underline{k}}{dt} = - \frac{\partial \omega}{\partial \underline{x}} ; \quad \frac{d\underline{x}}{dt} = \frac{\partial \omega}{\partial \underline{k}} = \underline{v}_{gr}$$

Snell's Law

group velocity

$\underline{k} = \underline{\nabla} \phi \Rightarrow$ phase front
orientation

$\underline{x} \Rightarrow$ position of
phase front.

check: IF analogy is valid, should be able
to derive eikonal equations from $\partial \Phi = 0$

$$\underline{\Phi} = \int dt \left[\underline{k} \cdot \dot{\underline{x}} - \omega(\underline{k}, \underline{x}) \right]$$

$$\delta \Phi = \int dt \left[\underline{h} \cdot \delta \dot{\underline{x}} + \delta \underline{h} \cdot \dot{\underline{x}} - \left(\frac{\partial \omega}{\partial \underline{x}} \cdot \delta \underline{x} + \frac{\partial \omega}{\partial \underline{h}} \cdot \delta \underline{h} \right) \right]$$

$$\delta \underline{x} = \delta \underline{h} = 0 \quad \text{at end-points}$$

⇒

$$\delta \Phi = \int dt \left[\left(\underline{h} \cdot \frac{d}{dt} \delta \underline{x} - \frac{\partial \omega}{\partial \underline{x}} \cdot \delta \underline{x} \right) + \left(\dot{\underline{x}} - \frac{\partial \omega}{\partial \underline{h}} \right) \cdot \delta \underline{h} \right]$$

cbp

$$\delta \Phi = \left. \underline{h} \cdot \delta \underline{x} \right|_{t_1}^{t_2} + \int dt \left[\left(\frac{d\underline{h}}{dt} + \frac{\partial \omega}{\partial \underline{x}} \right) \cdot \delta \underline{x} + \left(\dot{\underline{x}} - \frac{\partial \omega}{\partial \underline{h}} \right) \cdot \delta \underline{h} \right]$$

⇒

$$\delta \underline{x}, \delta \underline{h} \neq 0, \Rightarrow$$

$$\frac{d\underline{h}}{dt} = - \frac{\partial \omega}{\partial \underline{x}}, \quad \frac{d\underline{x}}{dt} = \frac{\partial \omega}{\partial \underline{h}}$$

so \rightarrow eikonal equations are Hamiltonian equations

\rightarrow eikonal equations extremize $\bar{\Phi}$.

\rightarrow its eikonal equations satisfy Liouville's Theorem

the "flow" in phase space $\underline{k}, \underline{x}$ is incompressible

$$\frac{\partial}{\partial k} \cdot \frac{d\underline{k}}{dt} + \frac{\partial}{\partial x} \cdot \frac{d\underline{x}}{dt} = -\frac{\partial^2 \omega}{\partial k \partial x} + \frac{\partial^2 \omega}{\partial x \partial k}$$

$$= 0$$

\therefore so if define wave density $\rho(\underline{k}, \underline{x}, t)$

then $\frac{\partial \rho}{\partial t} + \underline{D} \cdot (\underline{V} \rho) = 0$

but $\underline{D} \cdot \underline{V} = 0$

$$\underline{V} = \left[\frac{d\underline{x}}{dt}, \frac{d\underline{k}}{dt} \right]$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \underline{V} \cdot \underline{D} \rho = 0$$

$$\frac{\partial \rho}{\partial t} + \underline{v}_{gr} \cdot \frac{\partial}{\partial \underline{x}} \rho = - \frac{\partial \omega}{\partial \underline{x}} \cdot \frac{\partial \rho}{\partial \underline{k}} = 0$$


⇒ Vlasov-like equation for evolution of ρ

but... what is ρ ?

→ physical argument:

have $\frac{d\rho}{dt} = 0$ → conservation/invariance principle

Now, recall for oscillator with slowly varying parameters



$l = l(t)$

$$\frac{1}{l(t)} \frac{dl}{dt} \ll \omega = \sqrt{g/l}$$

then $\frac{d}{dt} (E/\omega) = 0$

$E/\omega \equiv \text{Action}$ (dims energy * time)

$$E = 2 \cdot \frac{1}{2} m \omega^2 l^2 \Theta^2 = m g l \Theta^2$$

$$\Rightarrow \frac{E}{\omega} = m\sqrt{g} l^{3/2} \omega^2$$

$$\Rightarrow d(E/\omega) = 0 \Rightarrow \frac{3}{2} l^{1/2} \frac{dl}{dt} + l^{3/2} \frac{d\omega^2}{dt}$$

$$d\omega^2/dt = -\frac{3}{2} \frac{1}{l} \frac{dl}{dt} \rightarrow l \text{ shortened } (l < 0) \text{ amplitude increased}$$

$$\rightarrow l \text{ lengthened, amplitude decreased.}$$

Now, for waves argue analogue of action
 is wave action density $E/\omega = N$

E = energy density
 N = action density

so wave kinetic equation is:

$$\frac{\partial N}{\partial t} + v_{gr} \frac{\partial N}{\partial x} - \frac{\partial \omega}{\partial x} \cdot \frac{\partial N}{\partial k} = 0$$

and analogy with Vlasov equation is evident, i.e.

$$\frac{\partial f}{\partial t} + v \frac{\partial f}{\partial x} + \frac{q}{m} E \frac{\partial f}{\partial v} = 0.$$

$$\frac{dh}{dt} = - \left(\frac{\partial \omega}{\partial x} \right)_h \Rightarrow \text{no conflict with } \frac{\partial h}{\partial t} = - \frac{\partial \omega}{\partial x}$$

→ Now, if system independent of time, have:

$$\partial \omega / \partial t = 0$$

$$\begin{aligned} \frac{d\omega}{dt} &= \frac{\partial \omega}{\partial t} + \frac{\partial \omega}{\partial h} \frac{dh}{dt} + \frac{\partial \omega}{\partial x} \frac{dx}{dt} \\ &= - \frac{\partial^2 \omega}{\partial k \partial x} + \frac{\partial^2 \omega}{\partial k \partial x} = 0 \quad \checkmark \end{aligned}$$

$$\frac{dN}{dt} \Big|_{\text{rays}} = 0 \Rightarrow \frac{d}{dt} \left[\begin{array}{c} \Sigma \\ \bar{\omega} \end{array} \right] \Big|_{\text{rays}} = 0$$

$$\Rightarrow \frac{1}{\omega} \frac{d\Sigma}{dt} \Big|_{\text{rays}} - \frac{\Sigma}{\omega^2} \frac{d\omega}{dt} \Big|_{\text{rays}} = 0$$

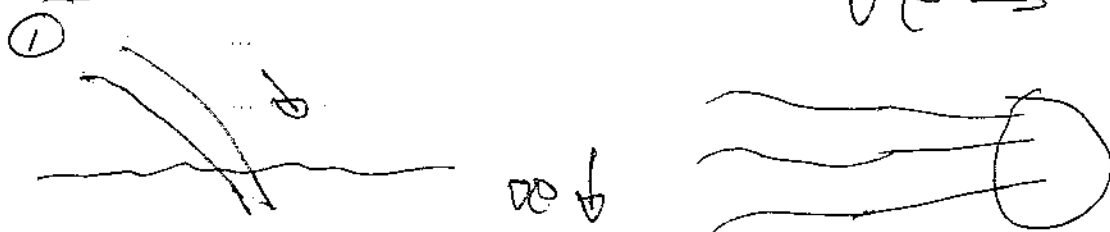
$$\Rightarrow \frac{\partial \Sigma}{\partial t} + \underline{v}_g \cdot \underline{\nabla} \Sigma - \frac{\partial \omega}{\partial x} \cdot \underline{\nabla}_h \Sigma = 0$$

and Liouville and integrate over $h \Rightarrow$

$$\frac{d\varepsilon}{dt} = \frac{\partial \varepsilon}{\partial t} + \nabla \cdot [V_g \varepsilon] = 0$$

applies to conservative case.

Applications



Alfvén wave packet incident on region with density increasing, field fixed.

c.e.

$$\nabla \cdot (V_g \varepsilon) = 0$$

$$\underline{B} = B \hat{z}$$

$$\frac{\partial}{\partial z} (V_A \varepsilon) = 0$$

$$V_A = B / \sqrt{4\pi\rho(z)}$$

$$V_{A\infty} \varepsilon_\infty = V_A(z) \varepsilon(z)$$

Inflow I

$$I = v_A(z) \Sigma(z)$$

$$= v_{A00} \sqrt{\frac{\rho_{00}}{\rho(z)}} \Sigma(z)$$

$$\Rightarrow \Sigma(z) = \left(\rho(z)/\rho_{00} \right)^{1/2} \Sigma_{00}$$

→ wave energy density increases in high density region

→ point is $v_{gr} \Sigma = \text{const}$

$v_{gr} = v_A \downarrow$ while $\rho \uparrow$, so Σ does increase

How about displacement?

- very roughly speaking:

as wave is linearization, and assumes/predicts certain phase relation,

→ linear wave theory valid for

$$|k \tilde{\xi}| < 1$$

↳ wave slope



If $k \tilde{\xi} \sim 1 \Rightarrow$ expect strongly nonlinear behavior, breaking, mixing etc.

n.b. though for Alfvén waves, need add parallel compressibility....

$$\begin{aligned} \text{Now } \Sigma(z) &= 2 \frac{\rho}{2} \tilde{\xi}^2 \\ &= \rho(z) \omega^2 \tilde{\xi}^2 \end{aligned}$$

Now $\omega = \text{const}$

$$\begin{aligned} \underline{\text{so}} \quad - \quad \tilde{\xi}^2 &= \frac{1}{\rho(z) \omega^2} \left(\frac{\rho(z)}{\rho_0} \right)^{1/2} \epsilon_0 \\ &= \frac{1}{\sqrt{\rho(z) \rho_0}} \frac{\epsilon_0}{\omega^2} \end{aligned}$$

∴ displacement drops $\sim \rho(z)^{-1/4}$

as wave propagates into high density region.

but $-$ slope $S \sim |k \tilde{\xi}|$

$$k = \frac{\omega}{v_A} = \frac{\omega}{v_{A0}} \sqrt{\frac{\rho(z)}{\rho_0}}$$

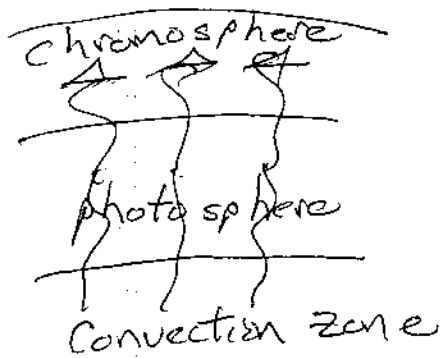
$$\underline{\text{so}} \quad |k \hat{\xi}| \sim \frac{\omega}{v_{A0}} \sqrt{\frac{\rho(z)}{\rho_0}} \left(\frac{E_0}{\omega}\right)^{1/2} \frac{1}{(\rho(z)\rho_0)^{1/4}}$$

$$\sim \rho(z)^{1/4}$$

\Rightarrow wave slope increases in high density region, as v_A changes

\Rightarrow Nonlinearity increases

② Sound propagating in chromosphere



$$\rho \sim e^{-z/H} \rightarrow \text{density decreases with height}$$

Sound waves emitted from convection zone (compressible convection) \rightarrow propagate into chromosphere

Take $T = \text{const} \Rightarrow c_s = \text{const.}$

Then $c_s E' = \text{const.}$

$$E(z) = \text{const.}$$

and $k = \omega/c_s = \text{const.}$

$$\underline{\text{so}} \quad \rho \tilde{\xi}^2 = \text{const.}$$

$$\rho(z) \omega^2 \tilde{\xi}^2 = \text{const.}$$

$$\Rightarrow \tilde{\xi} = \left(\xi_{\infty} / \rho(z) \omega^2 \right)^{1/2} \sim 1 / (\rho(z))^{1/2}$$

$$\text{or } k = \text{const.}, \quad k \tilde{\xi} \sim 1 / (\rho(z))^{1/2}$$

\Rightarrow - wave displacement increases in chromosphere

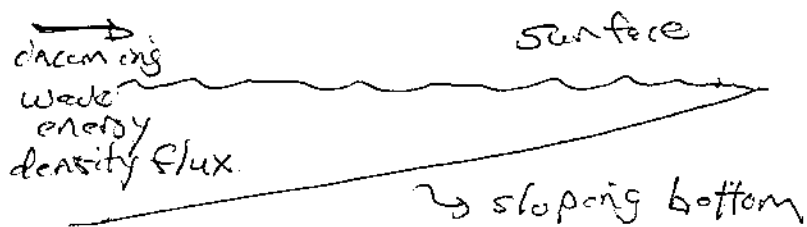
- sound wave simple \Rightarrow wave steepens and can shock

- physical picture is that of a whip \Rightarrow inertia at tip low, due tapering

- constitutes simple argument for chromospheric and possibly coronal heating by sound waves propagating from convection zone into upper layers.

(3) The beach...

Consider:



$$H = H(x)$$

Now, in shallow water
($\lambda > H$)



$$\frac{\partial h}{\partial t} + \frac{\partial (vh)}{\partial x} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = -g \frac{\partial h}{\partial x}$$

$$v = v_0 + \tilde{v}, \quad h = H + \tilde{h}$$

$$\Rightarrow \begin{aligned} -c\omega \tilde{h} + ikH \tilde{v} &= 0 \\ -c\omega \tilde{v} &= -ckg \tilde{h} \end{aligned}$$

$\therefore \rightarrow \omega^2 = k^2 g H$ is dispersion relation

\rightarrow analogy with acoustics is obvious

$$\begin{aligned} h &\leftrightarrow \rho & c_s^2 &= gH \\ v &\leftrightarrow v & & \text{etc.} \end{aligned}$$

$$\frac{\partial \tilde{v}}{\partial t} = -g \frac{\partial \tilde{h}}{\partial x} \quad (1)$$

$$\frac{\partial \tilde{h}}{\partial t} = -H \frac{\partial \tilde{v}}{\partial x} \quad (2)$$

$$\Rightarrow (1) \times \tilde{v} + (2) \times \left(g \frac{\tilde{h}}{H} \right)$$

$$\therefore \frac{\partial \tilde{v}^2}{\partial t} = -g \tilde{v} \frac{\partial \tilde{h}}{\partial x}$$

$$\frac{g}{H} \frac{\partial \tilde{h}^2}{\partial t} = -\frac{gH}{H} \tilde{h} \frac{\partial \tilde{v}}{\partial x}$$

$$\therefore \frac{\partial}{\partial t} \left(\frac{\tilde{v}^2}{2} + \frac{g\tilde{h}^2}{2H} \right) + \frac{\partial}{\partial x} \left(g\tilde{h}\tilde{v} \right) = 0$$

is energy theorem

$$\Rightarrow \Sigma = \frac{\tilde{v}^2}{2} + \frac{g\tilde{h}^2}{2H} \quad \text{is wave energy density}$$

$$\omega/k = (gH)^{1/2} \quad \text{is wave phase velocity}$$

so ... as no explicit time dependence:

$$\frac{\partial \Sigma}{\partial t} + \nabla \cdot (v_{gr} \Sigma) = 0$$

$$\Rightarrow v_g(x) \Sigma(x) = v_{\infty} \Sigma_{\infty} = I$$

$$\therefore \sqrt{gH(x)} \Sigma(x) = I$$

\Rightarrow as $x \rightarrow$ shore, $v_g \downarrow$ so $\Sigma(x)$ must increase

$$\Sigma(x) = \frac{\tilde{v}^2}{2} + g \frac{\tilde{h}^2}{2H} = \overline{\tilde{v}^2}$$

\rightarrow horizontal displacement

$$\tilde{v} = \frac{\partial \Sigma}{\partial t}$$

$$\Sigma(x) = \rho_0 \omega^2 \overline{\tilde{\epsilon}^2} \quad \text{and } \rho_0 \omega^2 = \text{const, here}$$

$$\Rightarrow \tilde{\Sigma}_{rms} \sim \left(\frac{I}{\rho_0 \omega^2 \sqrt{gH(x)}} \right)^{1/2} \sim H(x)^{-1/4}$$

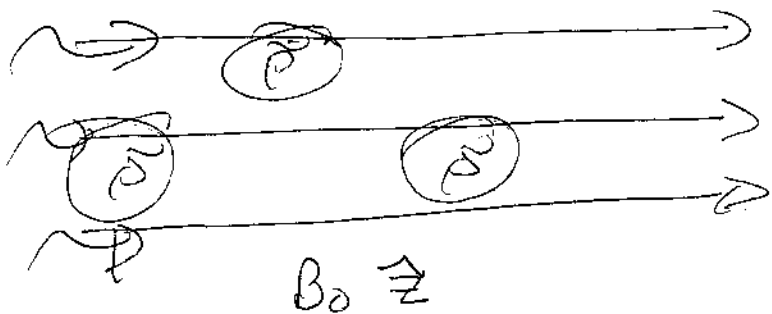
for profile $H(x)$, can deduce displacement profile

N.B. If $H = H(x, y)$, wavefronts align with bottom depth, via refraction.

$$\text{i.e. } \frac{dk}{dt} = -\frac{\partial \omega}{\partial x} = -\frac{\partial}{\partial x} \left[(gH(x, y))^{1/2} k \right]$$

(4) Alfven Waves in Random Medium

Consider straight B_0 threading medium
with space-time dependent inhomogeneities



i.e. $\rho_0 + \tilde{\rho}$

with $\langle \tilde{\rho}^2 \rangle_{q, \Omega}$ given

How does spectrum of Alfven waves evolve?

Assume: $|q| \ll |k|$
 $\Omega \ll |k v_A|$ } \rightarrow clear scale separation
between scatterer
and scatter-ee.
and weak inhomogeneities
($\rho \ll \rho_0$)

What happens?

$$\frac{dx}{dt} = v_{gr} = v_A$$

$$\frac{dk}{dt} = -\frac{\partial}{\partial x} \cdot (k_{||} v_A)$$

$$v_A = \frac{B_0}{\sqrt{4\pi\rho}} \approx v_{A0} \left(1 - \frac{\rho}{2\rho_0} \right)$$

take 1.0 for simplicity:

$$\frac{dz}{dt} = v_{A0} \left(1 - \frac{1}{2} \frac{\tilde{\rho}}{\rho_0} \right) = v_{A0} (1 - \delta\rho)$$

$$\frac{dk_z}{dt} = - \frac{\partial}{\partial z} \left(k_z v_{A0} \left(1 - \frac{\tilde{\rho}}{2\rho_0} \right) \right)$$

refraction
action

$$= \frac{\partial}{\partial z} \left(k_z v_{A0} \frac{\tilde{\rho}}{2\rho_0} \right) = \frac{\partial}{\partial z} k_z v_{A0} \delta\rho$$

How does Alfvén spectrum respond to this?

⇒ wave kinetics!

$$\frac{\partial N}{\partial t} + \underline{v}_g \cdot \nabla N - \frac{\partial \omega}{\partial x} \cdot \frac{\partial N}{\partial k} = 0$$

$$N = \sum(k, x) / \omega$$

$$\frac{\partial N}{\partial t} + v_{A0} (1 - \delta\rho) \hat{z} \cdot \nabla N + \frac{\partial}{\partial z} \left(k_z v_{A0} \delta\rho \right) \frac{\partial N}{\partial k_z} = 0$$

Now $\delta\rho$ is - random variable
- spectrum specified

∴ for trends need average

⇒

$$\frac{\partial \langle N \rangle}{\partial t} + \left\langle v_{A0}(1-d\rho) \bar{z} \cdot \delta N \right\rangle + \left\langle \frac{\partial}{\partial z} \left(k_z v_{A0} d\rho \right) \frac{\delta N}{\partial k_z} \right\rangle = 0$$

and average contributions will come from

$\langle d\rho \delta N \rangle$ type correlations.

∴ proceed in spirit of quasi-linear theory.

Using $\nabla_{\perp} \cdot \underline{v}_{\perp} = 0 \Rightarrow$

$$\frac{\partial \langle N \rangle}{\partial t} - \frac{\partial}{\partial z} \left\langle v_{A0} d\rho \delta N \right\rangle + \frac{\partial}{\partial k_z} \left\langle \frac{\partial (k_z v_{A0} d\rho)}{\partial z} \delta N \right\rangle = 0$$

where we have taken $\langle N \rangle$ indep. of z
(uniform beam).

Now, to calculate correlations $\langle d\rho \delta N \rangle$,

$\left\langle \frac{\partial d\rho}{\partial z} \delta N \right\rangle$, use linear response for δN

Linearizing WKE:

$$\frac{\partial \delta N}{\partial t} + v_A \frac{\partial \delta N}{\partial z} = v_A \frac{\partial \rho}{\partial z} \frac{\partial \langle N \rangle}{\partial z} - \frac{\partial (k_z v_A \delta \rho)}{\partial z} \frac{\partial \langle N \rangle}{\partial k_z}$$

homogeneous background

$$\Rightarrow -i(\Omega - z v_A) \delta N_{\Omega, z} = -iz k_z v_A \delta \rho_{\Omega, z} \frac{\partial \langle N \rangle}{\partial k_z}$$

$$\therefore \delta N_{\Omega, z} = \frac{z k_z v_A \delta \rho_{\Omega, z}}{(\Omega - z v_A)} \frac{\partial \langle N \rangle}{\partial k_z}$$

\Rightarrow

$$\frac{\partial \langle N \rangle}{\partial t} = \frac{\partial}{\partial k_z} D_{k_z} \frac{\partial \langle N \rangle}{\partial k_z} \quad \leadsto \text{quasi-linear diffusion equation for } \langle N \rangle$$

$$D_{k_z} = \sum_{\Omega, z} z^2 k_z^2 v_A^2 |\delta \rho_{\Omega, z}|^2 \pi \delta(\Omega - z v_A)$$

$$= \sum_z \pi k_z^2 z^2 v_A^2 |\delta \rho_{z v_A}|^2$$

resonance between

$$\frac{\Omega}{z} \text{ and } v_{gr} = v_A$$

stream field phase velocity \rightarrow packet group velocity.

Note:

- basic gist of answer to question is that random inhomogeneities diffuse $\langle N \rangle$ spectrum in k_z
- physics clear from treating eikonal equation as Langevin equation

i.e.

$$\frac{dk_z}{dt} = -\frac{\partial}{\partial z} V_A(z)$$

$$= -\frac{\partial}{\partial z} \left(V_A \left(1 - \frac{1}{2} \frac{\delta^2}{\delta z^2} \right) \right) k_z$$

k_z in k_z due to inhomog.

$$\frac{dk_z}{dt} = V_{A0} k_z \frac{\partial}{\partial z} \delta^2$$

stochastic refraction

$$\Rightarrow \langle dk_z^2 \rangle \approx D t$$

$$D \approx V_{A0}^2 k_z^2 \left\langle \frac{\partial}{\partial z} \delta^2 \right\rangle^2 \tau_c = D_{kz}$$

- what is τ_c ?

\Rightarrow set by spectrum of inhomogeneities

c.e. here Ω, \mathcal{E} independent

\rightarrow scatterers not waves \rightarrow width $\Delta \mathcal{E}$

$$\infty \neq |\tilde{\rho}_{\mathcal{E}, \Omega}^{\sim}|^2 = |\tilde{\rho}(\mathcal{E})|^2 \frac{\Delta \Omega}{\Omega^2 + (\Delta \Omega)^2}$$

$$\text{then } \tau_c = \min \left\{ \frac{1}{\Delta \Omega}, \frac{1}{\Delta \mathcal{E} V_A} \right\}$$

contrast to usual case:

$$\frac{\partial \langle F \rangle}{\partial t} = \frac{\partial}{\partial V} D \frac{\partial \langle F \rangle}{\partial V}$$

$$D = \sum_{\mathbf{k}} \frac{q^2}{m^2} |E_{\mathbf{k}}|^2 \pi \delta(\omega_{\mathbf{k}} - kv)$$

$$\text{and } \tau_{c0} \sim |k(V_{ph} - V_{gr})|^{-1}$$

\hookrightarrow dispersion time for eigenmode packet

when is QLT applicable? - $\left\{ \begin{array}{l} \text{equivalent to asking} \\ \text{when valid to treat} \\ \text{problem as stochastic} \end{array} \right.$

— basically, ① weak scattering
② resonance overlap

most clearly seen in context of particle



$$\tau_{sc} < \tau_{bounce}$$

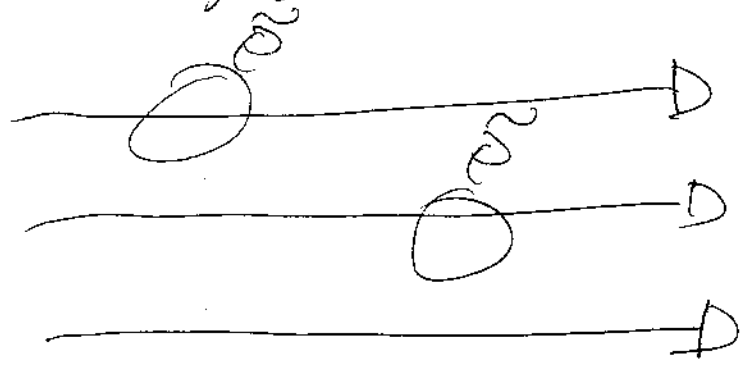
$$1/\tau_{bounce} \sim k (g\mu/m)^{1/2}$$

so linearization valid.

→ What is the bottom line? ⇒ spectrum spreads diffusively

in particular, high kz 's generated.

⑤ Now, go one step further ----



c.i.e. waves ⊕
 Alfvén
 ion-acoustic waves

⇒ associate scattering field
 — not with randomly prescribed inhomogeneities

- rather, with a field of ion acoustic waves

so in 1D

→ high frequency, short wavelength Alfvén waves
and $\omega = k_z v_A$

→ low frequency, longer wavelength ion acoustic waves

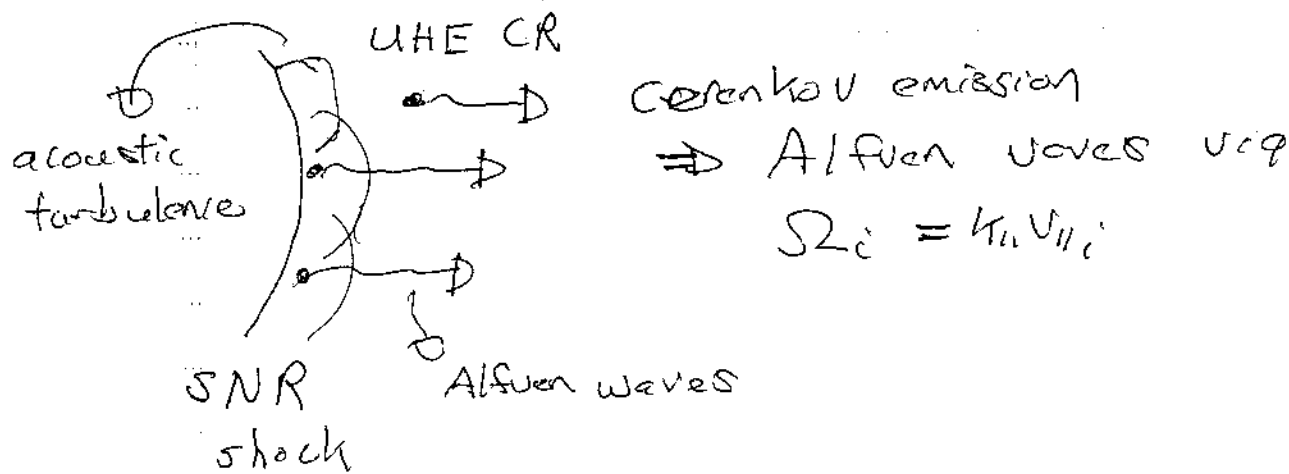
$$\Omega^2 = \frac{q^2 C_s^2}{1 + q^2 \lambda_D^2}$$

↳ dispersion due to Debye screening

- N.B.
- this is really a 'nonlinear' problem (very similar to SRS, SBS, Langmuir turbulence)
 - but, using eikonal methods, can be treated with linear, quasi-linear methodology
 - the "hidden smallness parameter" is scale ratio

$$\frac{\Omega}{\omega} < 1, \quad \frac{q}{k_z} < 1$$

- what might this be useful for, apart from trial-by-trial?



so - have environment where spectrum of Alfven waves co-exists with spectrum of acoustic-type density perturbations.

- interaction could be relevant to process of CR acceleration

N.B. Of course, it is a bit more complicated ...

→ What new feature enters here?

- eikonal games

- dynamical coupling of high and low frequency waves ↓

⇒ effective 'pressure' of Alfvén waves
on acoustic wave!

⊕

⇒ refraction of Alfvén waves by
acoustic waves as before

Now, in 1D, recall ion-acoustic wave
has:

$$\nabla^2 \tilde{\phi} = 4\pi n_0 |e| (\tilde{n}_i - \tilde{n}_e)$$

$$\frac{\tilde{n}_e}{n_0} = \frac{|e| \tilde{\phi}}{T_e} \quad (\omega \ll k v_{Te})$$

⇒ Boltzmann response

and for ions:

$$\frac{\partial n}{\partial t} + \frac{\partial (n v)}{\partial x} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = \left(\frac{|e| E}{m n} \right) - \frac{1}{n m} \frac{\partial p}{\partial x}$$

$$E = -\partial \phi / \partial x$$

To make easier, treat as 1 fluid, with dispersion later added "by hand".

⇒

$$\frac{\partial \rho}{\partial t} + \frac{d}{dx} (\rho v) = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} = -\frac{1}{\rho} \frac{\partial p}{\partial x}$$

i.e. magnetic field irrelevant to parallel-to- B_0 acoustic wave.

now here, have: $P = P_{Th}$.

With Alfvén waves (and ID), let

$$P \rightarrow P_{Th} + P_{AW_{eff}}$$

n.b. for technical reasons, need weak dispersion in Alfvén waves

$$\text{but } P_{AW_{eff}} = \epsilon_{AW}$$

$$\text{i.e. } \omega^2 = k_{||}^2 v_A^2 / (1 + k_{\perp}^2 c^2 / \omega_p^2)$$

↳ energy density of Alfvén waves

ignore till needed

$$= \int dk \omega_n N_n$$

↳ Action density of Alfvén waves.

so, in linear theory for acoustic wave:

$$\frac{\partial \tilde{p}}{\partial t} = -\rho_0 \frac{\partial \tilde{v}}{\partial x}$$

$$\frac{\partial \tilde{v}}{\partial t} = -\frac{1}{\rho_0} \frac{\partial}{\partial x} \left(\tilde{p} + \tilde{p}_{AW} \right)$$

$$\tilde{p} = \gamma \rho_0 \left(\tilde{v} / c_s \right)$$

$$\tilde{p}_{AW} = \int dk \omega_k \tilde{N}_k$$

from wave kinetic equation

⇒

$$\rho_0 \frac{\partial}{\partial t} \left(\frac{\partial \tilde{v}}{\partial x} \right) = -\frac{\partial^2}{\partial x^2} \left(\gamma \rho_0 \frac{\tilde{p}}{c_s} + \tilde{p}_{AW} \right)$$

$$\Rightarrow \frac{\partial^2}{\partial t^2} \tilde{p} = \frac{\partial^2}{\partial x^2} \left(\underbrace{\gamma \rho_0}_{c_s^2} \frac{\tilde{p}}{\rho_0} + \tilde{p}_{AW} \right)$$

Now, need calculate \tilde{p}_{AW} !

$$\frac{\partial N}{\partial t} + \underline{v}_{gr} \cdot \nabla N - \frac{\partial \omega}{\partial x} \frac{\partial N}{\partial k} = 0$$

and linearizing as before \Rightarrow

$$\frac{\partial \delta N}{\partial t} + v_A \frac{\partial \delta N}{\partial z} = - \frac{\partial}{\partial z} \left(k_z \frac{v_A \tilde{\rho}}{2\rho_0} \right) \frac{\partial \langle N \rangle}{\partial k}$$

\Rightarrow

$$\delta N_{\Omega, z} = \frac{z k_z v_A}{(\Omega - z v_A)} \left(\frac{\tilde{\rho}}{2\rho_0} \right)_{\Omega, z} \frac{\partial \langle N \rangle}{\partial k}$$

\therefore

$$-\Omega^2 \tilde{\rho}_{\Omega, z} = -z^2 \left(c_s^2 \tilde{\rho}_{\Omega, z} + \int dk_z (k_z v_A) \delta N_{\Omega, z} \right)$$

$$(\Omega^2 - z^2 c_s^2) \tilde{\rho}_{\Omega, z} = -z^2 \int dk_z (k_z v_A) \left(\frac{z k_z v_A / 2}{\Omega - z v_A} \frac{\tilde{\rho}_{\Omega, z} \partial \langle N \rangle}{\rho_0 z \partial k} \right)$$

\therefore

and convenient to write as

$$(\Omega^2 - g^2 c_s^2) \tilde{\rho}_{g,\Omega} = -g^2 \int dk_z \left[\frac{k_z v_A \langle N \rangle}{\rho_0} \right] \left(\frac{g k_z (v_A/2)}{\Omega - 2v_A} \right) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k} \tilde{\rho}_{g,\Omega}$$

$\{$
 $\frac{E_g/\rho_0 \sim P_{eff}}{\rho_0}$

⇒ have recovered a variant of Landau problem:

$$(\Omega^2 - g^2 c_s^2) = -g^2 \int dk_z \left(\frac{P_{eff}}{\rho_0} \right) \left(\frac{g k_z (v_A/2)}{\Omega - 2v_A} \right) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

→ effective "radiation pressure" of Alfvén waves modifies acoustic mode

→ $v_A = \Omega(g)/g$ resonance

⇒ Landau-like growth/damping

key is $\left. \frac{\partial \langle N \rangle}{\partial k} \right|_{res.} \Leftrightarrow \text{akin } \left. \frac{\partial f}{\partial v} \right|_{res.}$

Now, can proceed via P.T. if $P_{eff}/P_{th} < 1 \Rightarrow$

$$(\Omega_0 + i\gamma) - \Sigma^2 C_s^2 = -\Sigma^2 \int dk_z \left(\frac{P_{eff}}{P_0} \right) \frac{2k_z (V_A/2)}{\Omega - 2V_A} \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

$$i 2 \Sigma C_s \gamma = \Sigma^2 \int dk_z \left(\frac{P_{eff}}{P_0} \right) \frac{2k_z V_A}{2} \pi \delta(\Omega - 2V_A) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

$$\Rightarrow \gamma_z = \frac{\Sigma^2}{C_s} \left(\frac{P_{eff}}{P_0} \right) \frac{V_A}{4} \int dk_z k_z \pi \delta(\Omega - 2V_A) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

???

- point here is that no way to resolve/understand singularity, as Alfven waves are non-dispersive!

- one solution: go outside MHD to introduce dispersion!

i.e. retaining Hall term \Rightarrow (i.e. earlier comment)

$$\omega^2 = k_z^2 V_A^2 / (1 + k_z^2 d_s^2)$$

$$d_s^2 = c^2 / \omega_{pi}^2$$

∴ then have:

$$\gamma_2 = \frac{g^2}{c_s^2} \left(\frac{P_{eff}}{P_0} \right) \frac{V_A}{4} \int dk_z k_z \pi C'(\Omega - \Sigma V_{gr}(k)) \frac{1}{\langle N \rangle} \frac{\partial \langle N \rangle}{\partial k}$$

and resonant k identified! → proceed w/ Landau

2 lessons:

→ population conversion, i.e. $\frac{\partial \langle N \rangle}{\partial k} > 0$, needed
for growth. Also
to $\partial f / \partial v > 0$.
resonance

→ makes important point that non-dispersive waves all strained at same rate, so no Doppler dispersion

⇒ non-dispersive waves steeper → shocks, etc. in MHD

→ can compute $\langle N \rangle$ evolution w/ QLT ,
 $\Omega(\Sigma)$ dispersion relevant.